

# Machine Protection System



- **Run Permit System (Software Based)(1 second)**
  - » Coordinates machine mode changes.
  - » Scans IOC configurations for Software Configuration errors.
  - » MPS interface for masking equipment inputs.
- **Beam Permit System (Next beam pulse, (20 microseconds))**
  - » Latches fault conditions until fault clears and Operator resets condition. **BEAM\_PERMIT\_LINK** carrier interrupted and inhibits beam through front end devices.
- **Fast Protect System (20 microseconds)**
  - » Inhibits beam for duration of macro pulse by disabling **FAST\_PERMIT\_LINK** carrier to the front end. Restores Fast Protect link for next pulse if fault restored to normal.

# Beam Permit System



- **Concentrates Permit Inputs**
- **Inhibits carrier link to disable beam – Operator Reset required to continue beam operations**
- **Devices bypassed by Key or PLC**
- **Inputs disabled by machine mode (event link)**
- **Equipment maintained in locked racks**
- **Documentation control of changes**
- **System verification after changes**

# Beam Permit Inputs



- Power supply Enabled status
- Magnet Current Comparators
- Valve Status
- RF Status
- Target Status
- Dump Status
- Timing System Status
- Vacuum Status
- Loss monitors
- Current monitors
- HARP
- SEM
- Beam Position Monitors
- Beam Loss Accounting system

# Fast Protect System



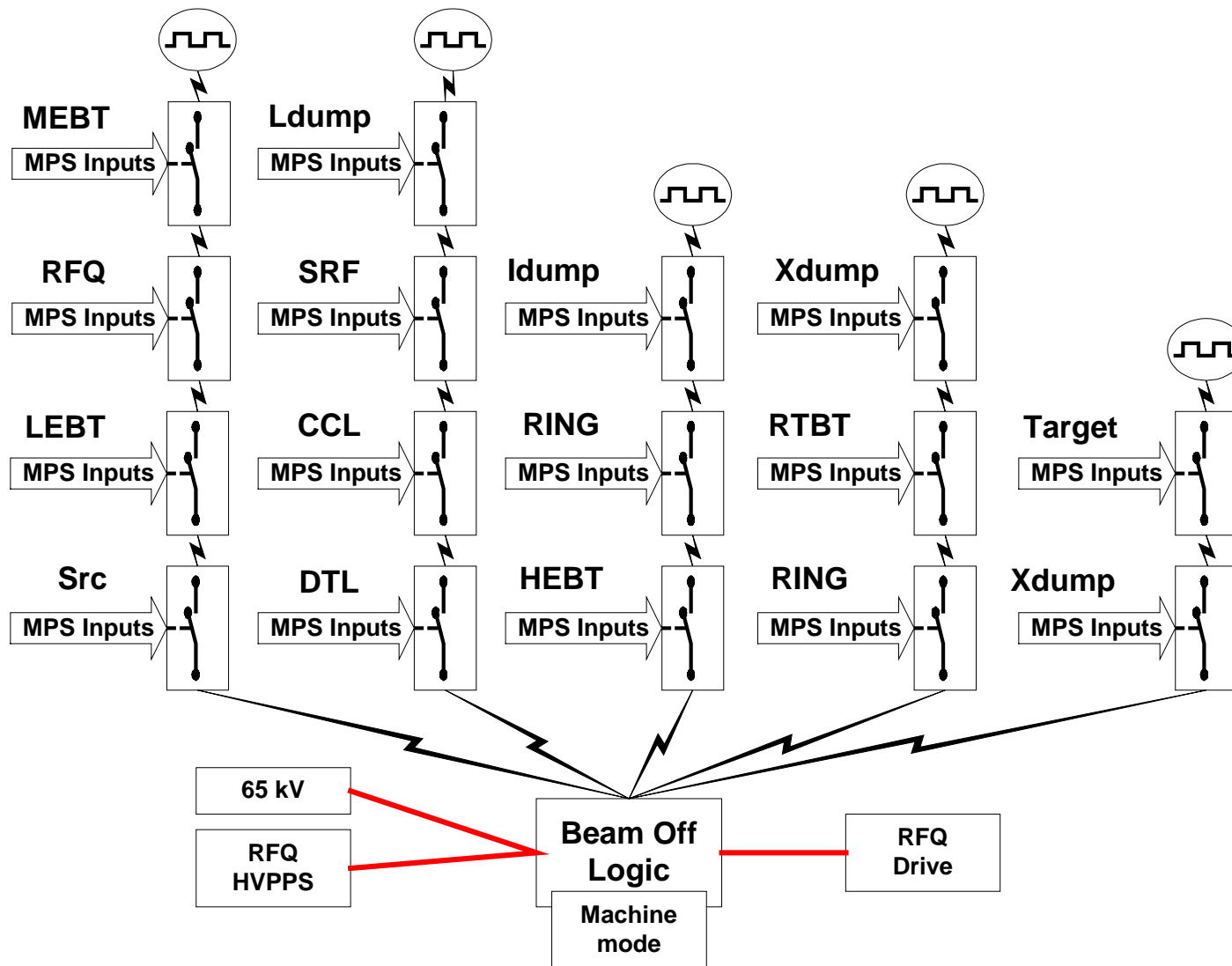
- **ALARA – Pulse Width Modulation**
- **Concentrates Permit Inputs**
- **Inhibits carrier link to disable Beam**
- **Inputs:**
  - » **Loss Monitors**
    - Software trip points, bypass
  - » **Beam position monitors**
    - Software trip points, bypass
  - » **RF Low level Controls**

# Automated Checkout Procedure

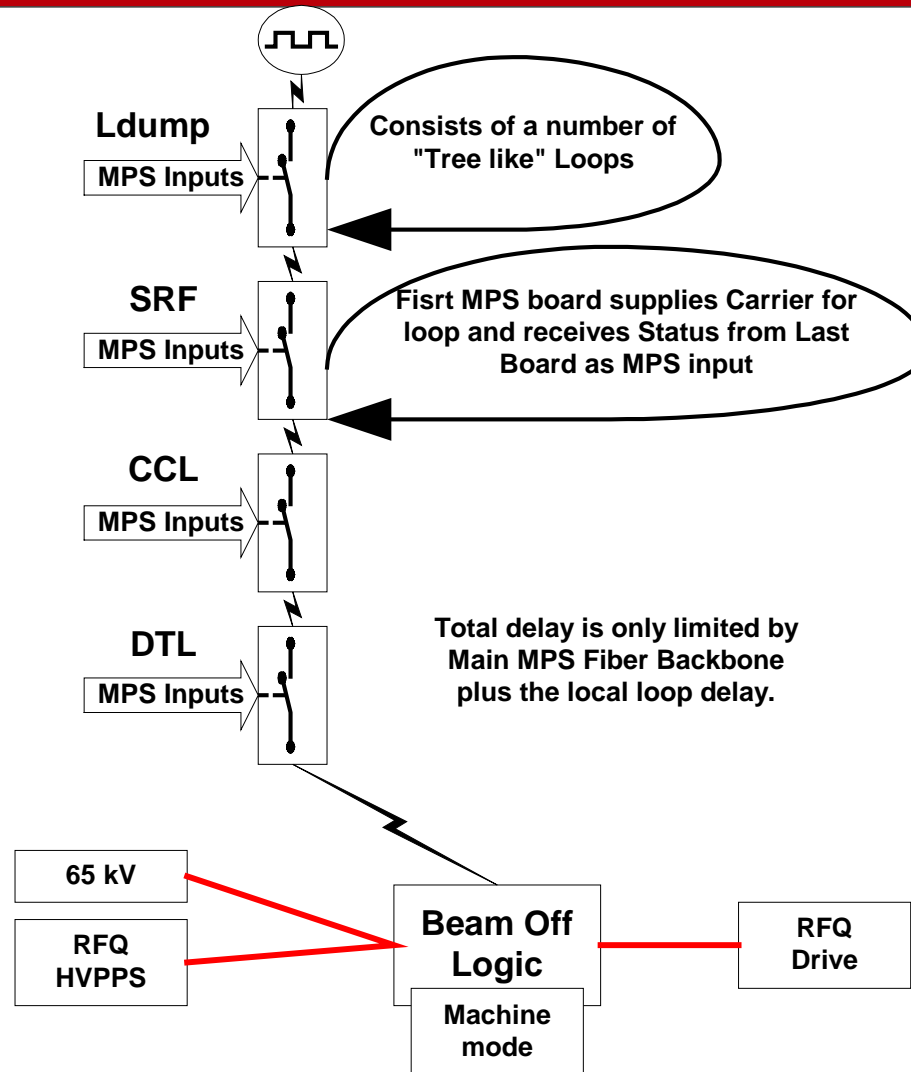


- Goal – Complete system checkout within 4 hours
- Check at sensor level when practical
  - » Inject current through toroid
  - » Current surge with high voltage ON (Loss monitors)
- Database (For each MPS input)
  - » MPS:Test\_Signal
  - » MPS:Reset
- Run Permit Sequencer Code
  - » For each PPS area
  - » Caput MPS:Trip\_Signal START
  - » Verify Front End Shutdown
  - » Caput MPS:Reset\_Signal DONE

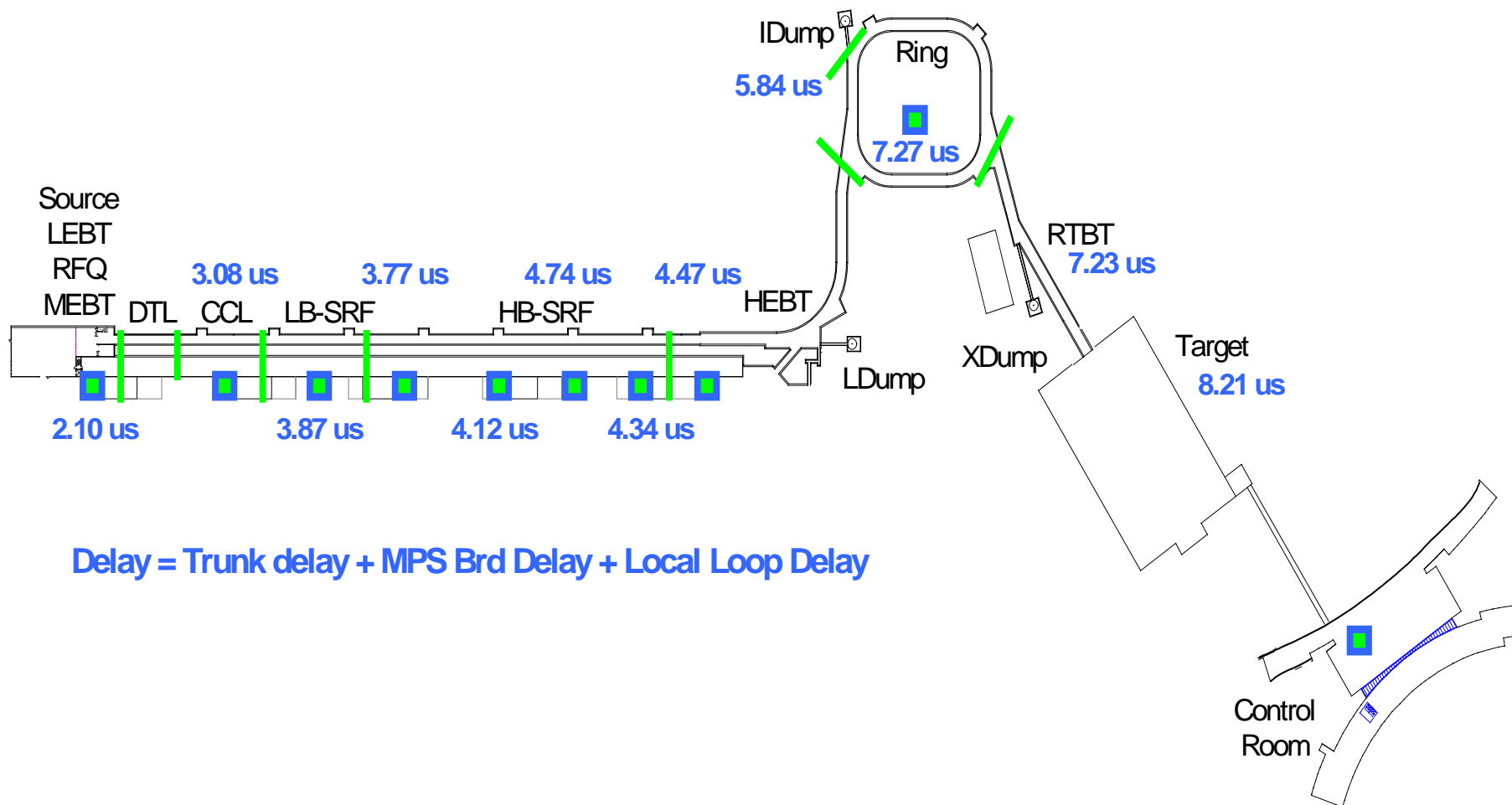
# Machine Protection System Links



# MPS Layout – Loops confined by Machine Mode



# MPS Carrier Cable Delays





# HEBT, Ring, RTBT MPS Layout considerations



## Linac Dump Mode

- Some HEBT devices, Ldump devices

## » Injection Dump Mode

- HEBT, Some Ring Devices, and Idump devices

## » Extraction Dump Modes

- Ring, Some RTBT Devices, and Xdump devices

## » Target Mode

- Ring, RTBT, and Target Devices

# MPS Chassis Inputs (Per System)



- Eight (8) positive true, fail-safe beam permit inputs.
- Eight (8) positive true, fail-safe fast protect inputs.
- One (1) 8 MHz carrier input, on-off modulation; beam permit link.
- One (1) 3 MHz carrier input, on-off modulation; fast protect link.
- One (1) 16 MHz carrier, bi-phase-mark modulated input event link.
- One (1) 10 MHz carrier, bi-phase-mark modulated input Real Time Data Link (RTDL).
- One (1) positive true, fail-safe PLC card bypass.

# MPS Module Outputs (Per System)



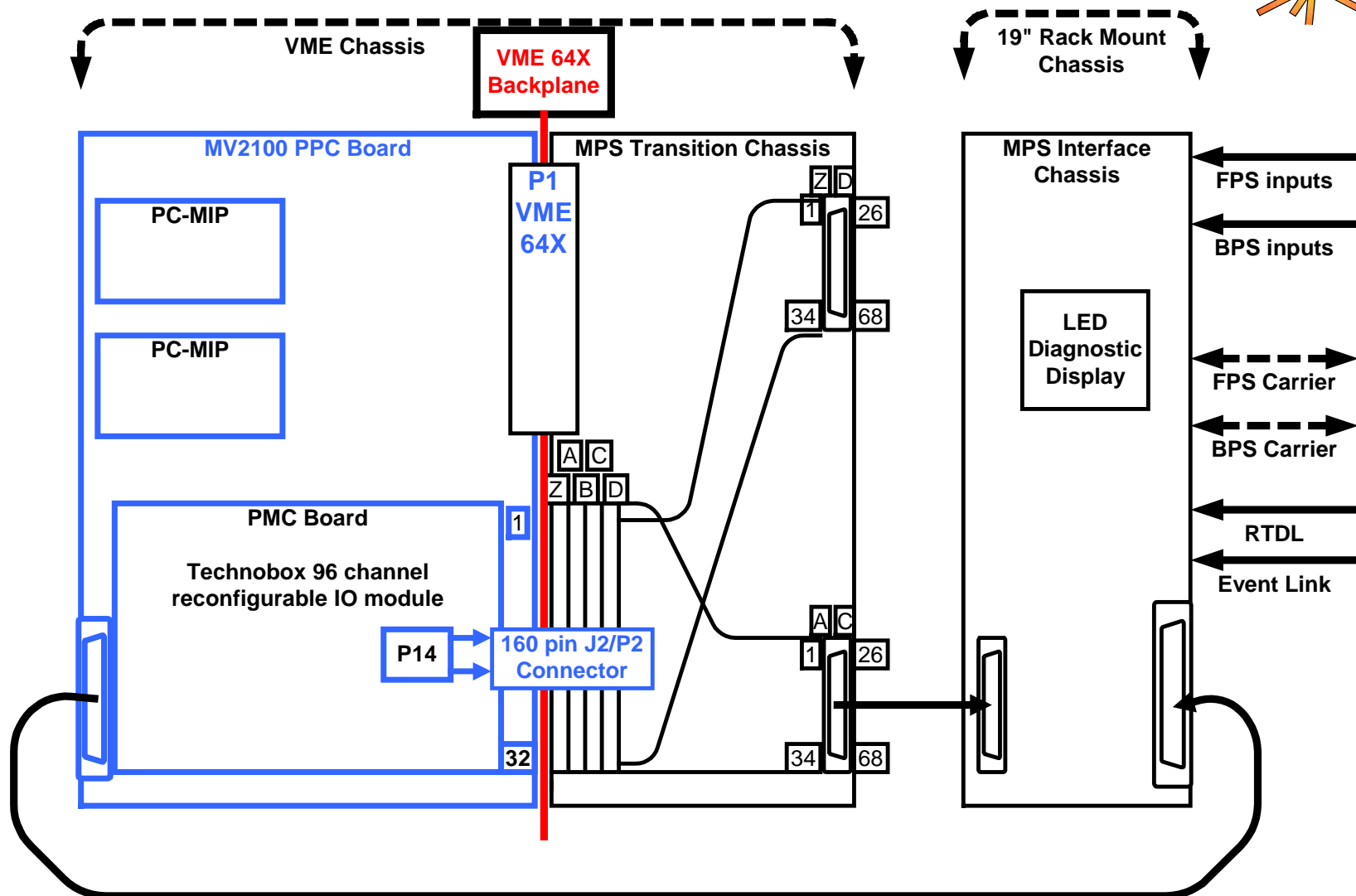
- One (1) 8 MHz carrier output, on-off modulation; beam permit link.
- One (1) 3 MHz carrier output, on-off modulation; fast protect link.
- Two (2) positive true, fail-safe, level output, local beam permit status.
- Two (2) positive true, fail-safe, level output, local fast protect status.
- One (1) positive true, fail-safe, level output, EVENT\_LINK input status.

# MPS Hardware 3 Component

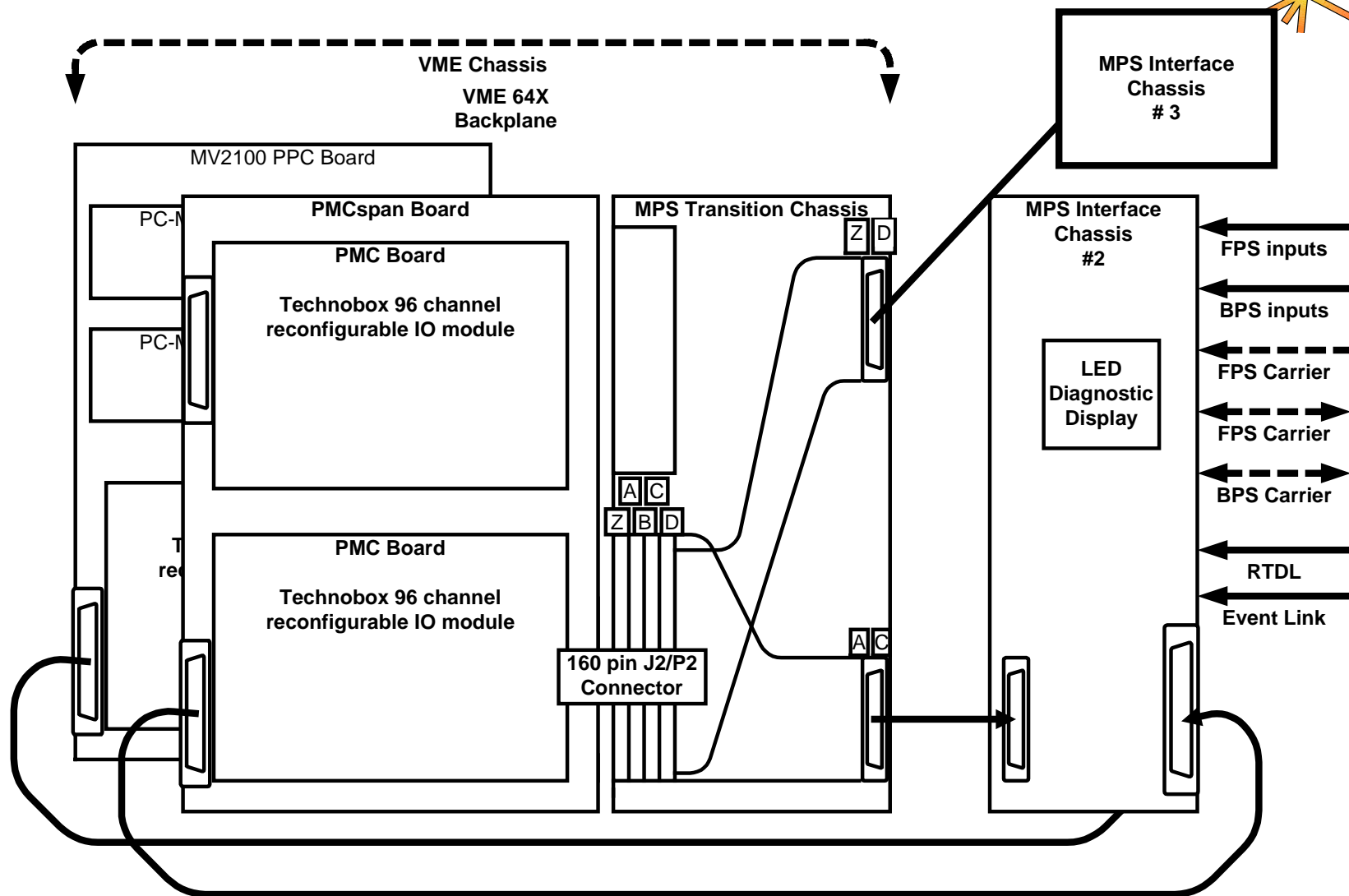


- MVME PPC 2100 – Uses PMC slot for Digital IO. Contains Digital Logic, Fault Timers, Interface Registers
- PMCspan – Motorola PMC expansion board. Used to add 2<sup>nd</sup> and 3<sup>rd</sup> MPS systems if required.
- P2 VME Transition Module – Routes P2 connections to 50 pin SCSI connector(s)
- MPS Interface Chassis – Interfaces MPS input signals, Carrier links, RTDL and Event Links to the PMC card for processing.

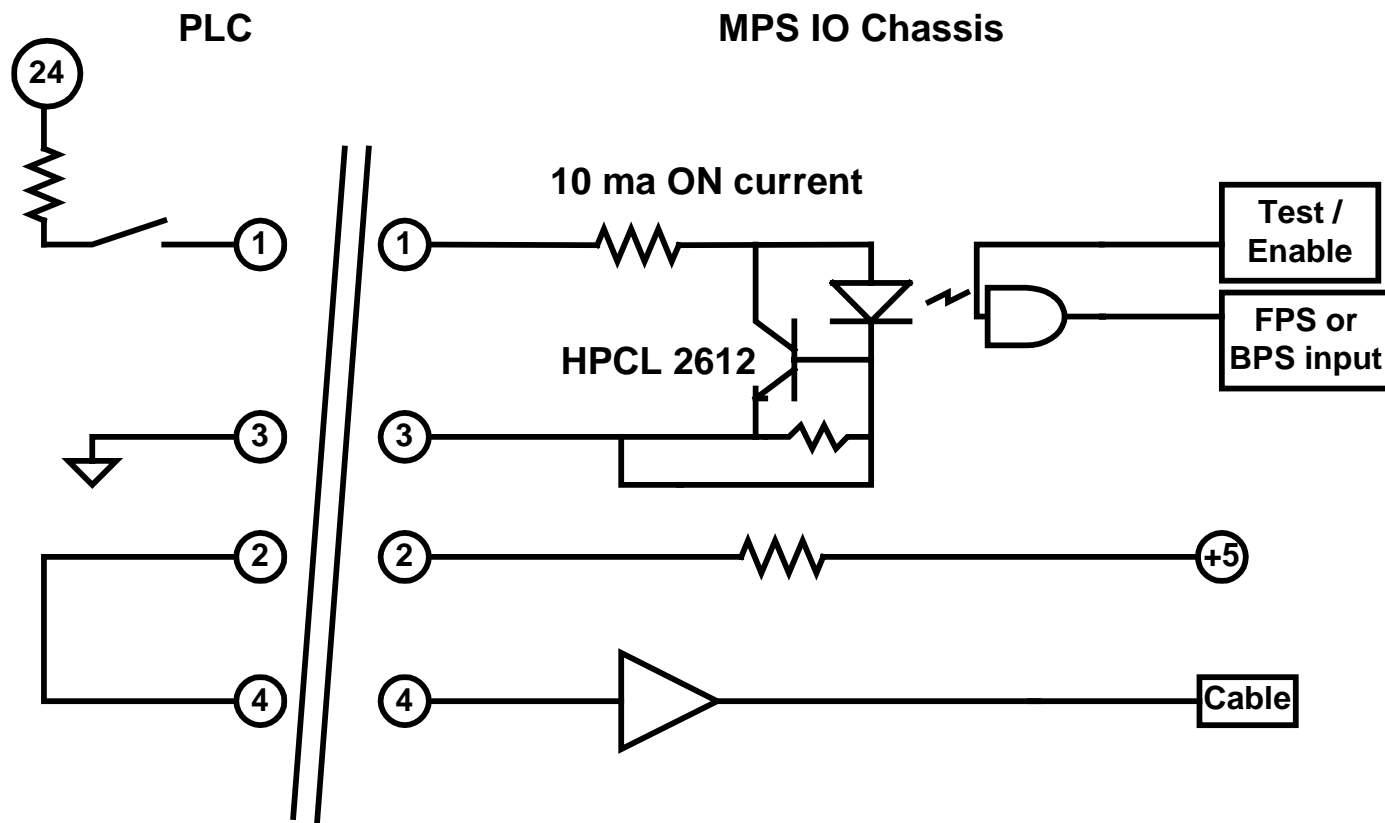
# MPS Hardware



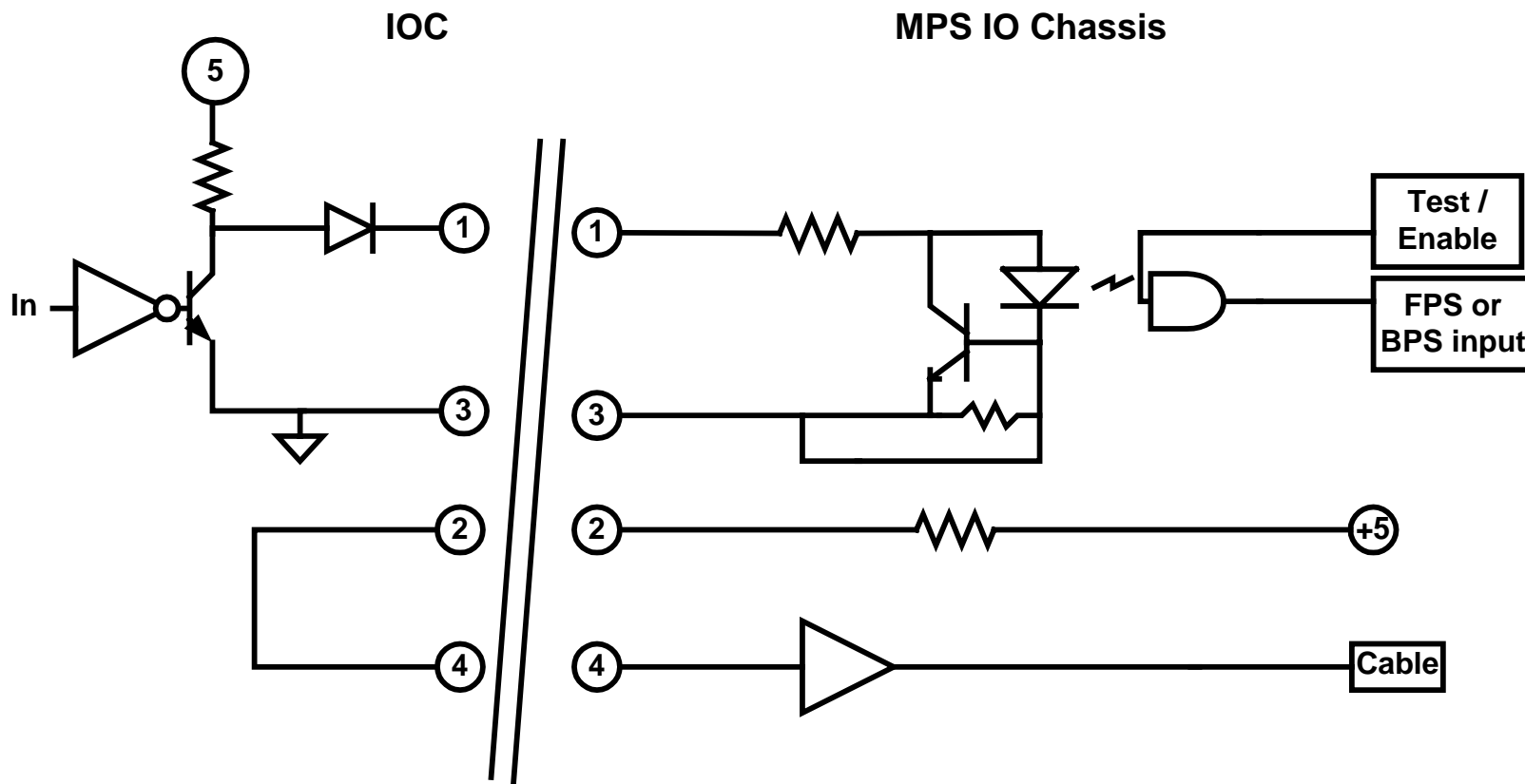
# MPS hardware – 3 system configuration



# MPS Input Circuit - PLC



# MPS Input Circuit - IOC





# IOC Digital OP circuit



## VMIC 2330 Digital OP module

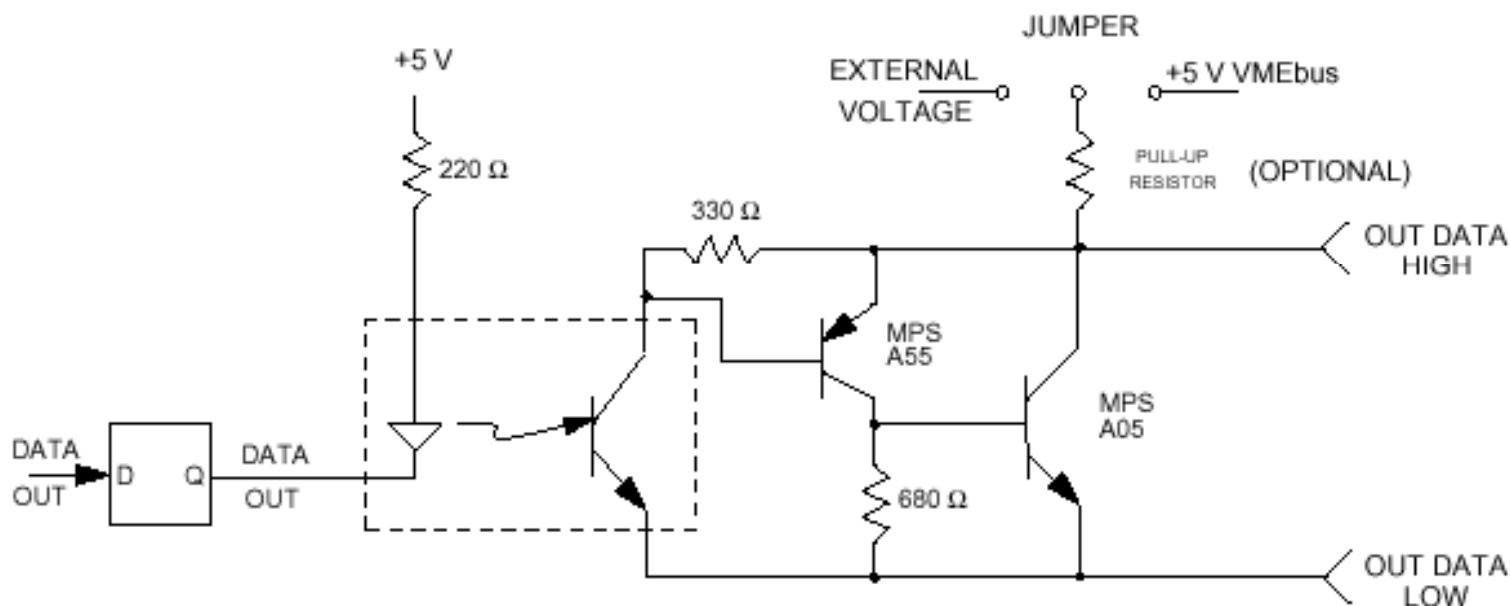
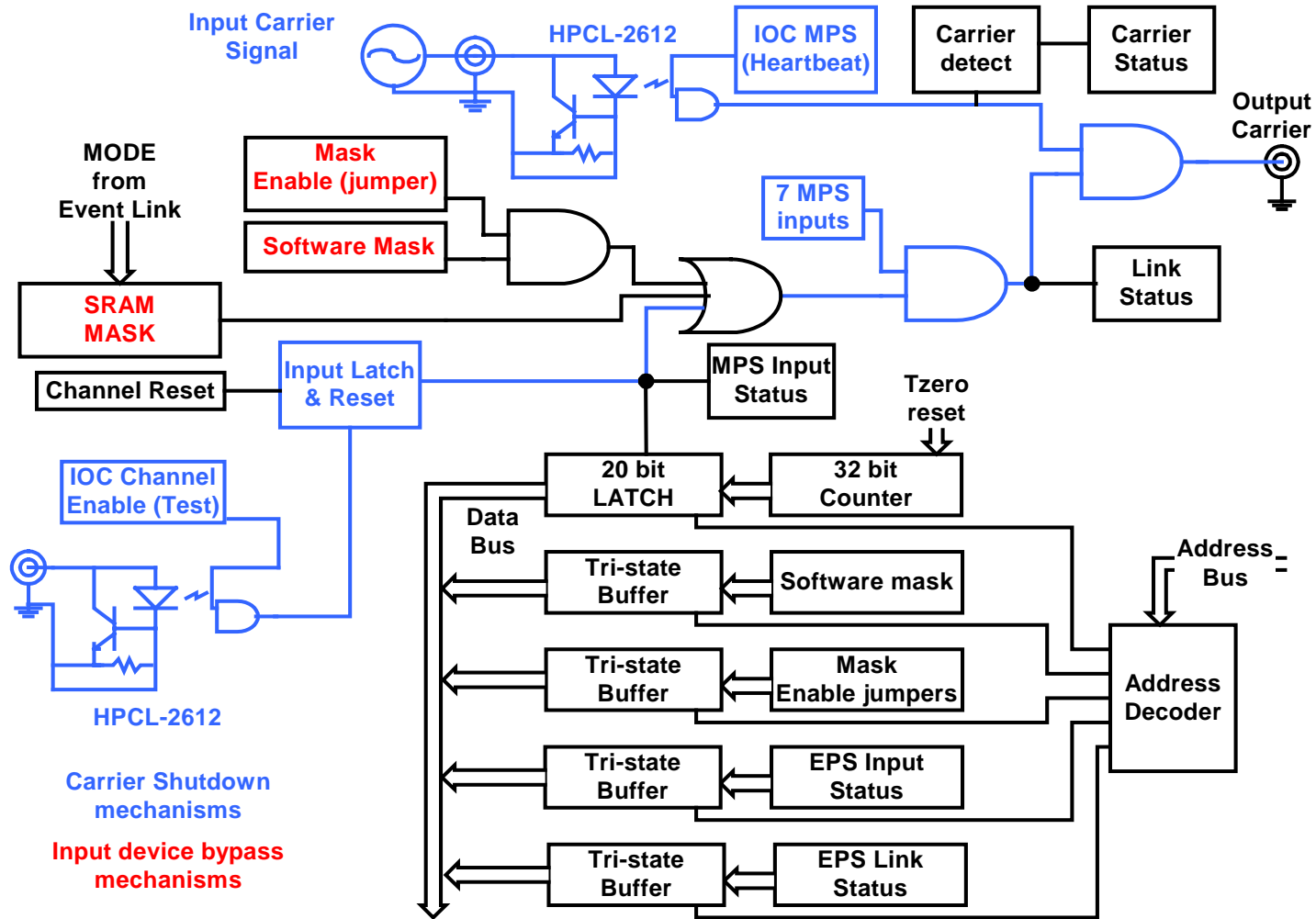


Figure 2. Typical Output Configuration

# MPS Input Channel (fast protect or beam permit)



# MPS Shutoff Equipment



- **Fast Protect**
  - » RF drive to RFQ
- **Beam Permit**
  - » 65 KV Power supply
  - » RFQ Power Supply
- **Run Permit**
  - » Fast Protect
  - » Beam Permit
- **( Beam Abort - Extraction Kickers )**
- **( Event System (Abort signal) )**

# Ring MPS Devices



- Vacuum System
- Extraction Kickers
- Collimators Motion, Temperature
- Stripper Foils – Integrity, Motion
- Timing System Status
- Ring RF System
- DCCT current sensors
- Integrating current monitors

# Vacuum System MPS inputs



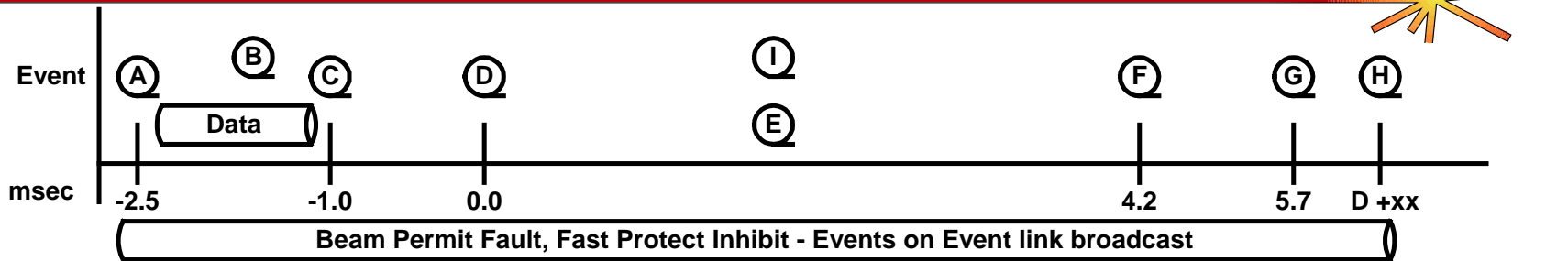
- Valve Controls (~1 msec response from time valve starts to close)
- Vacuum Pumps (Slow Response, seconds)
- Vacuum Levels Beam can be allowed to run for different periods of time depending on the vacuum levels. Will co-ordinate with loss monitors.
  - »  $10^{-6}$  ASAP
  - »  $10^{-7}$  ? Many instabilities
  - »  $10^{-8}$  ? Limited Running
  - »  $10^{-9}$  OK
- USE SNS PLC Programming Standards
- MPS Test Functions programmed in to PLC code
- PLC can SUM MPS inputs within the same Machine Mode Zone

# Extraction Kicker issues



- Kicker Charging Power Supply Status
- Kicker Ready Status – pulse to pulse – MPS input triggered by Tzero Event?
- False firing – Abort ASAP
- Beam Abort, Fault – ASAP verses waiting until “Normal” extraction time? Separate hardware input triggers? Different Events?
- 1 Kicker off line
- Extraction timing – Defined from Tzero “Event” on event link

# SNS System Timing Cycle



## A. Start of Cycle (Also End of Cycle)

- Previous pulse information sent out (RTDL)
- Information about next pulse sent out (RTDL)
- Time Stamp sent out (RTDL)

## B. Information Events

- Mode information sent out (Event link) – One of 32 predefined beam modes, indicating pulse type and beam line (dump) in use.
- Synchronous Events – 1 Hz, 10 Hz, Snapshot

## C. RTDL data valid – Hardware can load registers with data from the RTDL

## D. Tzero – All time stamp registers loaded, fast counters initialized. Parameters for the next pulse are frozen.

## E. Beam Permit Faults, Fast Protect aborts, and beam veto's can come at any time.

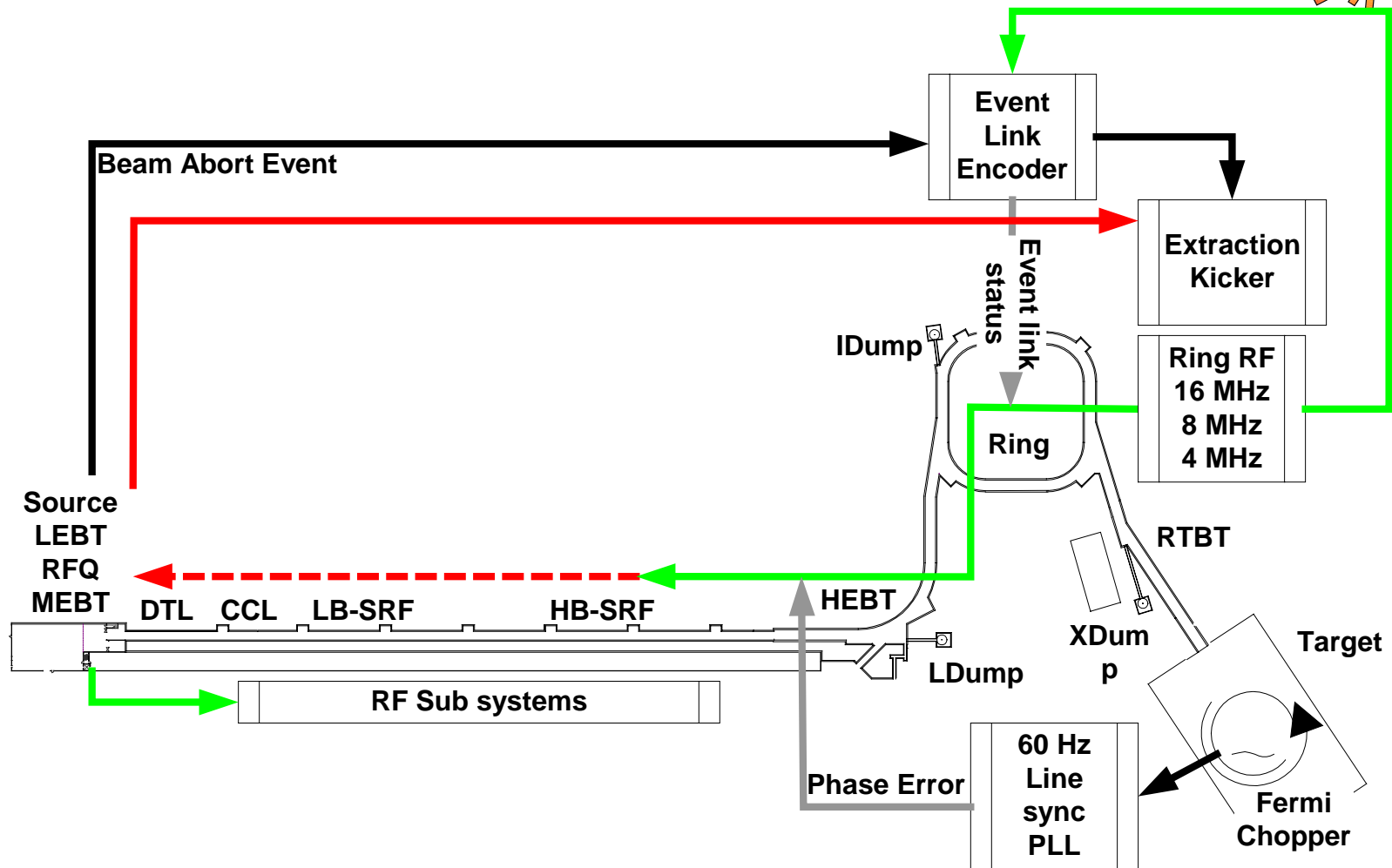
## F. Beam inject – Injection cycle starts

## G. Injection complete or Beam off.

## H. Extraction – From 10 turns to 1000's of turns after injection cycle complete, nominally 10 turns.

## I. Subsystem specific events for subsystem synchronous triggers, trouble shooting, etc.

# Kicker Abort Signals, Event link and/or Hard wired SNS





# Ring Collimator MPS Inputs



- Temperature sensors
- Water Flow ?
- Normal loss monitors? (Dynamic range OK?)
- Motion – (Drop to lower beam power?)
- Motion out of range (LVDT's?)
- Limit Switches

# Injection Foil



- Foil Failure
  - » Beam Loss Monitors
  - » HARPS
  - » Integrating Current Monitor
  - » Peak Current Monitor
  - » Foil Video monitor
- Foil Motion –
  - » Low power mode required?
  - » LVDT – Motion range available
  - » Limit Switches

# Ring RF MPS Considerations



- RF Power Supply
- RF Cavity Field Error Signals
- Reflected Power
- RF Phase Error monitoring
- RF – Beam phase monitoring?
- RF Power Ramping (Amplitude modulation?)